

# MOTÓMAN YRC1000

Industrial Robot Controller



## High Performance Controller YRC1000 for MOTOMAN Robots

The MOTOMAN YRC1000 is a compact, fast and flexible controller for MOTOMAN robots that combines high performance robot control in a small footprint cabinet with volume of 125 litres and a maximum weight of 70 kg.

Besides the typical YASKAWA controller functionality, the YRC1000 includes additional functional improvements. Speed of the controller has been increased by lowering a ladder scanning time.

Path accuracy improvement assures increased precision in trajectory performance independently on the motion speed.

User interface supports smartphone like touch operations and allows the user to 3D simulate robots motion on PP screen before and during execution of the real robot arm. Service staff can directly connect to the PP user interface for remote service purposes. Total programming pendant's weight was reduced to 730 grams which offers more convenient use by the operator. The new controller simplifies maintenance by offering preventive maintenance information and powerful software tools for analysis and notification.

#### **KEY BENEFITS**

- Compact, fast and flexible
- Global standardization (no transformer required)
- High path accuracy
- High efficiency

## **Optimal Industrial Design**

• Volume: 125 liters



## Programming Pendant (PHG) – ergonomical, light and easy



• Help function



	Specifications Controller YRC1000		
	Dimensions	598 (W) x 490 (H) x 427 (D) mm (125 I without protrusion parts)	
	Mass	70 kg max. (possible to control three external axes)	
	Cooling system	Indirect cooling	
	Ambient temperature	During operation: 0°C to +45°C / During storage: -10°C to +60°C	
	Relative humidity	90 % max. (non-condensing)	
	Power supply	Three-phase 380-440 VAC (+10 %, -15 %), 50/60 Hz (±2 %)	
	Digital I/Os	Specialized signals: 19 inputs and 6 outputs / General signals: 40 inputs and 40 outputs	
	Programming capacity	JOB: 200,000 steps, 10,000 instructions / CIO ladder: 20,000 steps	
	Expansion slots	2 x PCIe or 2 x PCI or 1 x PCI/1 x PCIe	
	LAN (Connection to host)	2 (10BASE-T/100BASE-TX)	
	Interface	RS-232C/RS422: 1 ch (used by switching)	

## Common Size for use in Japan, Asia, Europe, and the U.S.



## Improved Programming Pendant



Specifications Programming Pendant			
Dimensions	152 (W) x 299 (H) x 53 (D) mm		
Mass	0.730 kg		
Material	Reinforced plastics		
Operation Device	Select keys, axis keys, numerical/application keys, mode selector switch with keys (mode: teach, play, and remote), emergency stop button, enable switch, SD card interface device, USB port (1 port)		
Display	5.7-inch color LCD, touch panel 640 x 480 pixels		
IEC Protection Class	IP54		

## MOTOMAN YRC1000 – Options

## YRC1000 Design Concept



## YRC1000 Standalone

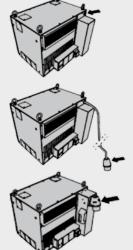
### Master cabinet standalone:

- In case that YRC1000 is a main cabinet in the system (i.e. Main switch of the cabinet is also main switch of the whole system), YRC1000 cannot stand on the servicing level directly
- EN 60204-1 states minimum position of the system's main switch with respect to the servicing level, as well as minimum height of cables connected to the cabinet above the servicing level



Dimensions in mm

## YRC1000 Power Supply Variants



### 1. Direct connection (standard):

- Connection is made directly to the main switch, the cable goes through an opening at the back side of the YRC1000 cabinet at the upper right corner
- Connection inside the controller can be made by electrician only

### 2. CEE connector with a cable (option):

- YASKAWA can deliver YRC1000 cabinet with CEE socket, plug and cable (L = 5 m)
- No additional wiring in the controller is needed

### 3. CEE connector at the cabinet (option):

- CEE socket is mounted at the CEE hood at the back side of the YRC1000 cabinet
- No additional wiring in the controller is needed

## YRC1000 Robot Cable Variants





#### 1. Straight cable at controller side/straight cable at robot side:

- Robot cable connector is straight on controller side
- Robot cable connector is straight on robot side
- This configuration does allow any space under the cable and cable connector
- This configuration may restrain area behind the controller due to the robot cable bending ratio (R = 270 mm)

### 2. Angled cable at controller side/straight cable at robot side:

- Robot cable connector is angled on controller side
- Robot cable connector is straight on robot side
- This configuration requires free space under the cable and cable connector
- Can be used in case that YRC1000 controller is elevated by means of socket cabinet or other stand
- This configuration does not require additional space behind the controller other than free space required by mounting instructions (cooling of the cabinet)

## YRC1000 Controller Module Options

Visual	Name	Dimension	ArtNo. 1	ArtNo. 2
	Socket cabinet with angled connector plate	H = 250 mm	183292	143815100
	Cabinet with angled connector plate	H = 499 mm	183294	143816100
	Cabinet without angled connector plate		183293	143817100
	Cabinet with angled connector plate, double height	H = 989 mm	187153	143816110

## MOTOMAN YRC1000 – Options

## YRC1000 Socket Cabinet Options

Visual	Name	Description	ArtNo. 1	ArtNo. 2
	Drawer for socket cabinet	Backside of the cabinet, drawer used for easy access into the socket (mounting of IO terminals)	187154	143818100
	Mounting plate in socket cabinet, C-rail and other components	Fixing element in the dawer	187155	143889100



## YRC1000 H = 499 mm and H = 989 mm Cabinet Options

Visual	Name	Description	ArtNo. 1	ArtNo. 2
· · · ·	Swing frame for standard cabinet, H = 499 mm	Inside the cabinet for easy access, plate for IO terminals mounting	187156	144270100
	Swing frame (high) for double height cabinet, H = 989 mm		187157	144270110

## YRC1000 Option Cabinet - available Equipment

#### Master cabinet with socket cabinet:

#### Socket cabinet with height of 250 mm

- 4 x IO transfer element (with and without relay)
- Full version of Cable Set A incl. FSU signals
- Full version of Cable Set B
- FSU transfer element
- Conveyor cabling
- Connectors for external axes (max. 3)



## Master cabinet with option cabinet H = 499 mm with or without angled connector plate:

#### Option cabinet with height of 499 mm

- 4 × IO transfer element (with and without relay) on a swing frame
- Full version of cable set A incl. FSU
- Full version of cable set B
- FSU transfer element
- Conveyor cabling
- Connectors for external axes (max. 3)
- Additional IO board
- Mounting plate for additional equipment
- Mounting plate as a swing frame for additional equipment (option)



### Master cabinet with option cabinet H = 989 mm:

#### Option cabinet with height of 989 mm

- $4 \times IO$  transfer element (with and without relay) on a swing frame
- Full version of cable set A incl. FSU
- Full version of cable set B
- FSU transfer element
- Conveyor cabling
- Connectors for external axes (max. 3)
- Additional IO board
- Mounting plate for additional equipment
- Mounting plate as a swing frame for additional equipment (option)







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